

① H is solⁿ set of $\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 1 & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= -2x_4 \\ x_2 &= -x_3 \\ x_3, x_4 &\text{ free} \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_4 \begin{bmatrix} -2 \\ 0 \\ 0 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}$$

So a) $\dim H = 2$

b) $\left\{ \begin{bmatrix} -2 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\}$ is a basis for H

② $\begin{bmatrix} 3 & 3 & 0 & 6 & 0 \\ 1 & 1 & 4 & 0 & 0 \\ 0 & 0 & 5 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$

a) Rows in RREF containing pivots: $\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$

b) $x_1 = -x_2$
 $x_3 = 0$
 $x_4 = 0$
 $x_2, x_5 \text{ free}$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} x_2 + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} x_5 \quad \text{so basis } \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

c) Columns in A containing pivots: $\left\{ \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 6 \\ 1 \end{bmatrix} \right\}$

$$\textcircled{3} \quad a) \dim \text{Ker } T + \dim \text{Ran } T = \dim W$$

$$0 + \dim \text{Ran } T = 3$$

$$\text{so } \dim \text{Ran } T = 3$$

b) Since $\dim \text{Ran } T = 3$ but $\dim V = 4$
it is impossible for $\text{Ran } T$ to be V

$$\textcircled{4} \quad a) \det(A - \lambda I) = \begin{vmatrix} 6-\lambda & -1 \\ 4 & 2-\lambda \end{vmatrix} = (6-\lambda)(2-\lambda) + 4 \\ = 12 - 8\lambda + \lambda^2 + 4 \\ = \lambda^2 - 8\lambda + 16 \\ = (\lambda - 4)^2$$

the only eigenvalue of A is 4

$$b) \lambda = 4: (A - 4I)\vec{x} = \vec{0}$$

$$\begin{bmatrix} 2 & -1 \\ 4 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \vec{0}$$

$$\begin{bmatrix} 2 & -1 \\ 4 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 0 \end{bmatrix} \quad x_1 = \frac{1}{2}x_2 \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix}$$

Picking say $x_2 = 2$: $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ is an eigenvector with $\lambda = 4$

And the $\lambda = 4$ eigenspace is $\text{Span} \left\{ \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} \right\}$

c) A has only a single 1-dim eigenspace, $1 < 2$

so A is not diagonalizable

$$\textcircled{5} \quad \text{a) } \begin{vmatrix} 1 & 0 & 3 & 5 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 4 & 2 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & 3 & 5 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 4 & 2 \\ 0 & 0 & 0 & 2 \end{vmatrix} = - (1 \cdot 1 \cdot 4 \cdot 2) = -8$$

- b) Since $\det A \neq 0$, A is invertible so $5A$ is also invertible: $\text{rank } 5A = 4$
- c) Since $\det A \neq 0$, A is invertible so A^3 is also invertible: $\text{rank } A^3 = 4$
- d) Since $\det A \neq 0$, A is invertible so $\text{Ran } T = \text{Col } A = \mathbb{R}^4$

- \textcircled{6} a) $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ could have $\dim 0, 1$, or 2
 $(0 \text{ if } \vec{v}_1 = \vec{0} \text{ and } \vec{v}_2 = \vec{0}; 1 \text{ if } \vec{v}_1 \text{ is multiple of } \vec{v}_2 \neq \vec{0}; 2 \text{ if } \vec{v}_1, \vec{v}_2 \text{ lin indep})$
- b) $\vec{v}_1 - \vec{v}_2 = -(\vec{v}_1 + \vec{v}_2) + 2\vec{v}_1$ so $\vec{v}_1 - \vec{v}_2$ is a lin comb of \vec{v}_1 and $\vec{v}_1 + \vec{v}_2$
so $\text{Span}\{\vec{v}_1, \vec{v}_1 + \vec{v}_2, \vec{v}_1 - \vec{v}_2\} = \text{Span}\{\vec{v}_1, \vec{v}_1 + \vec{v}_2\}$
which could have $\dim 0, 1$, or 2 (just like previous part)

$$\textcircled{7} \quad \text{a) } T(p) = \begin{bmatrix} p(0) \\ p(1) \\ p(2) \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 0 \end{bmatrix}$$

- b) $T(p) = \vec{0}$ means $p(0) = 0, p(1) = 0, p(2) = 0$
so $p(t) = t(t-1)(t-2)(at^3 + bt^2 + ct + d)$
 $= a \cdot t^4(t-1)(t-2) + b \cdot t^3(t-1)(t-2) + c \cdot t^2(t-1)(t-2) + d \cdot t(t-1)(t-2)$
so $\{t^4(t-1)(t-2), t^3(t-1)(t-2), t^2(t-1)(t-2), t(t-1)(t-2)\}$
is a basis for $\text{Ker } T$

c) $\dim \text{Ker } T + \dim \text{Ran } T = \dim W$

$$4 + \dim \text{Ran } T = 7$$

$$\dim \text{Ran } T = 3$$

⑧

- a) FALSE (it can only be between 0 and 4)
- b) TRUE
- c) FALSE (can also be a point or the whole \mathbb{R}^3)
- d) TRUE ($A\vec{v} = \lambda\vec{v}$ $B\vec{v} = \mu\vec{v} \Rightarrow (A+B)\vec{v} = (\lambda+\mu)\vec{v}$)
- e) FALSE
- f) FALSE
- g) TRUE
- h) FALSE
- i) FALSE
- j) TRUE
- k) TRUE
- l) TRUE } (these two are really the same question)