

**M 382D: Differential Topology**  
**Spring 2015**

Exercise Set 7

Due: Wed Mar 25

**Exercise 1.** Give examples of the following.

1. A compact manifold  $M$  such that there does not exist a compact manifold  $N$  with boundary such that  $\partial N$  is diffeomorphic to  $M$ .
2. A connected noncompact manifold  $M$  with boundary such that  $\partial M$  is compact and connected.
3. A connected noncompact manifold  $M$  with boundary such that  $\partial M$  is noncompact and connected.

**Exercise 2.** This exercise constructs splittings of exact sequences of vector bundles. (In class we explained how to do this in a “geometric” way for the particular exact sequence defining the normal bundle to a submanifold.)

1. Suppose

$$0 \longrightarrow E' \xrightarrow{i} E \xrightarrow{j} E'' \longrightarrow 0$$

is a short exact sequence of vector spaces. Recall this means  $i$  is injective,  $j$  is surjective, and  $\ker j = i(E')$ . A *splitting* is a linear map  $s : E'' \rightarrow E$  which is right inverse to  $j$ , i.e.  $j \circ s = 1$ . Prove that the space of splittings is an affine space over the vector space  $\text{Hom}(E'', E')$ . Prove also that a splitting is equivalent to a left inverse to  $i$ .

2. Let  $A$  be a real affine space and  $a_1, \dots, a_n \in A$ . Suppose  $\rho_1, \dots, \rho_n \in \mathbb{R}$  satisfy  $\rho_1 + \dots + \rho_n = 1$ . Make sense of the element  $\rho_1 a_1 + \dots + \rho_n a_n \in A$ .
3. Now suppose  $M$  is a smooth manifold and

$$0 \longrightarrow E' \xrightarrow{i} E \xrightarrow{j} E'' \longrightarrow 0$$

a short exact sequence of vector bundles over  $M$ . Use a partition of unity argument to construct a splitting of this sequence.

**Exercise 3.** The *quaternions*  $\mathbb{H}$  are a division algebra over  $\mathbb{R}$  which is a 4-dimensional vector space with basis  $1, i, j, k$  and multiplication rule  $i^2 = j^2 = k^2 = -1$ ,  $ij = -ji = k$ ,  $jk = -kj = i$ ,  $ki = -ik = j$ . Construct a norm on the quaternions by setting  $|a + bi + cj + dk|^2 = a^2 + b^2 + c^2 + d^2$ , where  $a, b, c, d \in \mathbb{R}$ . Identify  $S^3$  as the unit sphere in  $\mathbb{H}$ . Use the quaternion multiplication to construct a global trivialization of  $TS^3$ , that is, three vector fields on  $S^3$  which for each  $p \in S^3$  form a basis of  $T_p S^3$ . (Hint: Warm up by replacing  $\mathbb{H}$  with  $\mathbb{C}$  and  $S^3$  with  $S^1$ .)

**Exercise 4.** Suppose  $M$  is a smooth manifold,  $f : M \rightarrow \mathbb{R}$  and  $g : M \rightarrow \mathbb{R}^k$ . Show that  $d(fg) = fdg + gdf$  (and explain what this equation means).