

Tangent spaces

$f: M \rightarrow N$ should have a corresponding df which maps "vectors on M based at p " to "vectors on N based at $f(p)$ "

$$df: T_p M \rightarrow T_{f(p)} N$$

"tangent space"



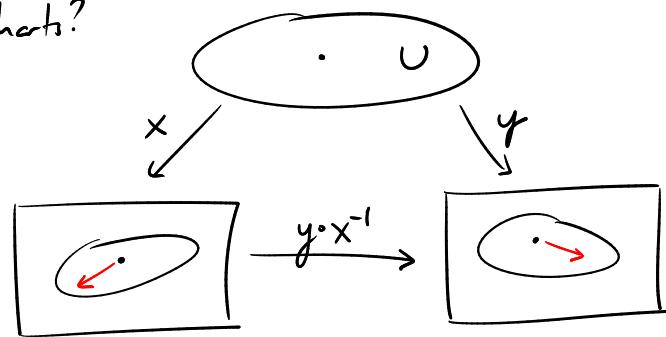
How to formulate this?

Idea: given a chart (U, x) on M with $p \in U$, should be able to identify $T_p M$ with the vector space \mathbb{R}^n .

But how do we compare different charts?

Use the map $d(y \circ x^{-1})$.

Precisely:



Def M a smooth mfd with atlas $\mathcal{C} = \{(U_\alpha, x_\alpha)\}_{\alpha \in A}$, $p \in M$: let $m = \dim_M(p)$

$$T_p M = \{(\alpha, \xi): \alpha \in A \text{ with } p \in U_\alpha, \xi \in \mathbb{R}^m\} / \sim \quad \text{where } (\beta, \xi) \sim (\alpha, d(x_\alpha \circ x_\beta^{-1}) \xi)$$

Prop $T_p M$ is a vector space, with a canonical isomorphism $j_\alpha: T_p M \xrightarrow{\sim} \mathbb{R}^m$

$$\text{for each } \alpha \in A \text{ with } p \in U_\alpha, \text{ and } j_\alpha \circ j_\beta^{-1} = d(x_\alpha \circ x_\beta^{-1})_{x_\beta(p)}.$$

Pf Vector space structure: $(\alpha, \xi) + (\alpha, \xi') = (\alpha, \xi + \xi')$ and $\lambda \cdot (\alpha, \xi) = (\alpha, \lambda \xi)$

Define $j_\alpha(\alpha, \xi) = \xi$. Check it's \simeq .

$$\text{Then } j_\alpha \circ j_\beta^{-1}(\xi) = j_\alpha(\beta, \xi) = j_\alpha(\alpha, d(x_\alpha \circ x_\beta^{-1}) \xi) = d(x_\alpha \circ x_\beta^{-1}) \xi.$$

□

Practically speaking, this means: given a chart (U_α, x_α) we get a basis for $T_p M$.

Call the basis vectors $e_{\alpha i}$, $i=1,\dots,m$. The bases are related by $e_{\alpha i} = \frac{\partial x_\beta^j}{\partial x_\alpha^i} e_{\beta j}$

(implicit summation over j) (More precisely, $\frac{\partial x_\beta^j}{\partial x_\alpha^i}$ means $\frac{\partial}{\partial x_\alpha^i} [x_\beta \circ x_\alpha^{-1}]^j$), components of the map $\mathbb{A}^m \rightarrow \mathbb{A}^m$
 ↑ coordinates on \mathbb{A}^m

Def/Prop If $f: M \rightarrow N$ smooth, we define $df_p: T_p M \rightarrow T_{f(p)} N$ by

$$df_p = j_{\alpha'}^{-1} \circ d[x_{\alpha'} \circ f \circ x_\alpha^{-1}] \circ j_\alpha$$

for any α s.t. $p \in U_\alpha$

and α' s.t. $f(p) \in V_{\alpha'}$

This is well defined (doesn't depend on which α, α' we choose).

$$\begin{array}{ccc} M & \xrightarrow{f} & N \\ x_\alpha \downarrow & & \downarrow x_{\alpha'} \\ \mathbb{A}^m & \longrightarrow & \mathbb{A}^n \end{array} \quad \begin{array}{ccc} T_p M & \xrightarrow{df_p} & T_{f(p)} N \\ j_\alpha \downarrow & & \downarrow j_{\alpha'} \\ \mathbb{R}^m & \longrightarrow & \mathbb{R}^n \end{array}$$

Pf Changing α to β and α' to β' ,

$$\begin{aligned} j_{\beta'}^{-1} \circ d[x_{\beta'} \circ f \circ x_\beta^{-1}] \circ j_\beta &= j_{\alpha'}^{-1} \circ \underbrace{j_{\alpha'} \circ j_\beta^{-1}}_{d(x_{\alpha'} \circ x_\beta^{-1})} \circ d[x_{\beta'} \circ f \circ x_\beta^{-1}] \circ \underbrace{j_\beta \circ j_\alpha^{-1} \circ j_\alpha}_{d(x_\beta \circ x_\alpha^{-1})} \\ &= j_{\alpha'}^{-1} \circ d[x_{\alpha'} \circ f \circ x_\alpha^{-1}] \circ j_\alpha \end{aligned} \quad \blacksquare$$

Def If $f: M \rightarrow \mathbb{R}$ smooth then get

$$df_p: T_p M \rightarrow T_{f(p)} \mathbb{R} \xrightarrow{\sim} \mathbb{R} \quad [\text{since } \mathbb{R} \text{ has a canonical chart}]$$

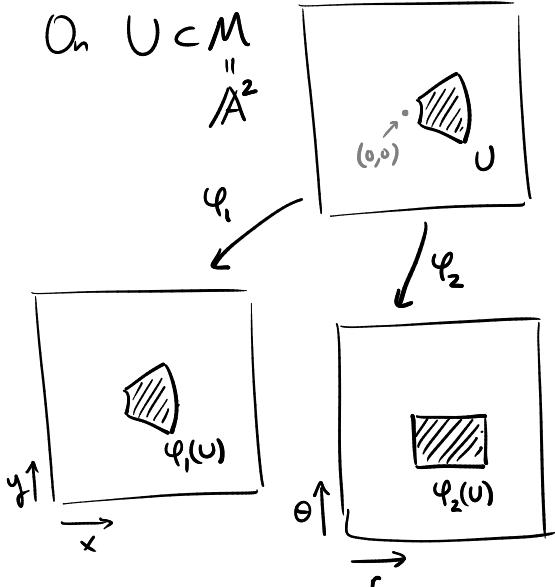
For $\xi \in T_p M$ we write ξf for $df_p(\xi)$ (directional derivative).

Prop If $\xi = \xi_\alpha^i e_{\alpha i}$ then $\xi f = \xi_\alpha^i \frac{\partial f}{\partial x_\alpha^i}$. (More precisely: $\frac{\partial f}{\partial x_\alpha^i}$ means $\frac{\partial}{\partial x_\alpha^i} f \circ x_\alpha^{-1}$)

Pf Exercise.

Rk Thus the basis vectors for $T_p M$ which we called $e_{\alpha i}$ could equally well have been called $\frac{\partial}{\partial x_i}$. This is a popular notation.

Ex On $U \subset M \cong \mathbb{A}^2$



two charts: $(U, (\overset{\varphi_1}{x}, \overset{\varphi_1}{y}))$ $(U, (\overset{\varphi_2}{r}, \overset{\varphi_2}{\theta}))$

overlap $\varphi_1 \circ \varphi_2^{-1}: (r, \theta) \mapsto (x, y) = (r \cos \theta, r \sin \theta)$ i.e. $x = r \cos \theta$
 $y = r \sin \theta$

$T_p M$ has 2 bases: $\left\{ \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\}$ and $\left\{ \frac{\partial}{\partial r}, \frac{\partial}{\partial \theta} \right\}$

$$\begin{aligned} \text{related by e.g. } \frac{\partial}{\partial r} &= \frac{\partial x}{\partial r} \cdot \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \cdot \frac{\partial}{\partial y} \\ &= \cos \theta \cdot \frac{\partial}{\partial x} + \sin \theta \cdot \frac{\partial}{\partial y} \end{aligned}$$

Rk There are alternative approaches: e.g.

- 1) define $T_p M$ as a space of derivations acting on C^∞ functions on M
- 2) define $T_p M$ as a space of equivalence classes of curves in M passing thru p

All are equivalent.